

THE MINIMAL POLYNOMIAL AND SOME APPLICATIONS

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1. INTRODUCTION

The easiest matrices to compute with are the diagonal ones. The sum and product of diagonal matrices can be computed componentwise along the main diagonal, and taking powers of a diagonal matrix is simple too. All the complications of matrix operations are gone when working only with diagonal matrices. If a matrix A is not diagonal but can be conjugated to a diagonal matrix, say $D := PAP^{-1}$ is diagonal, then $A = P^{-1}DP$ so $A^k = P^{-1}D^kP$ for all integers k , which reduces us to computations with a diagonal matrix. In many applications of linear algebra (*e.g.*, dynamical systems, differential equations, Markov chains, recursive sequences) powers of a matrix are crucial to understanding the situation, so the relevance of knowing when we can conjugate a nondiagonal matrix into a diagonal matrix is clear.

We want look at the coordinate-free formulation of the idea of a diagonal matrix, which will be called a diagonalizable operator. There is a special polynomial, the minimal polynomial (generally not equal to the characteristic polynomial), which will tell us exactly when a linear operator is diagonalizable. The minimal polynomial will also give us information about nilpotent operators (those having a power equal to O).

All linear operators under discussion are understood to be acting on nonzero finite-dimensional vector spaces over a given field F .

2. DIAGONALIZABLE OPERATORS

Definition 2.1. We say the linear operator $A: V \rightarrow V$ is *diagonalizable* when it admits a diagonal matrix representation with respect to some basis of V : there is a basis \mathcal{B} of V such that the matrix $[A]_{\mathcal{B}}$ is diagonal.

Let's translate diagonalizability into the language of eigenvectors rather than matrices.

Theorem 2.2. *The linear operator $A: V \rightarrow V$ is diagonalizable if and only if there is a basis of eigenvectors for A in V .*

Proof. Suppose there is a basis $\mathcal{B} = \{e_1, \dots, e_n\}$ of V in which $[A]_{\mathcal{B}}$ is diagonal:

$$[A]_{\mathcal{B}} = \begin{pmatrix} a_1 & 0 & \cdots & 0 \\ 0 & a_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & a_n \end{pmatrix}.$$

Then $Ae_i = a_i e_i$ for all i , so each e_i is an eigenvector for A . Conversely, if V has a basis $\{v_1, \dots, v_n\}$ of eigenvectors of A , with $Av_i = \lambda_i v_i$ for $\lambda_i \in F$, then in this basis the matrix representation of A is $\text{diag}(\lambda_1, \dots, \lambda_n)$. \square

A basis of eigenvectors for an operator is called an *eigenbasis*.

An example of a linear operator that is *not* diagonalizable over any field F is $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ acting on F^2 . Its only eigenvectors are the vectors $\begin{pmatrix} x \\ 0 \end{pmatrix}$. There are not enough eigenvectors to form a basis for F^2 , so $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ on F^2 does not diagonalize. Remember this example! Since $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$